Class inputs &outputs

# Route planner

* Input – arraylist of jobs
* Output – arraylist of type co-ordinate

# Job decider

* Input – text file
* Output – arraylist of jobs

# Job assignment

* Input – arraylist of jobs
* Output – HashMap(key = robot, value = jobs)

# Robot communicator

* Input – HashMap(key = robot, value = jobs)
* Output – hashmap (key = robot, value = object of type route)

# Server communicator

* Input – hashmap (key = robot, value = object of type route)
* Output – object of type route (instructions)

# Controller

* Input –
* Output –

# Robot movement

* Input –
* Output –

# Collision stopper

* Input –
* Output –

# Information organiser

* Input –
* Output –

# GUI user input

* Input –
* Output –